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EDUCATION

California Institute of Technology Pasadena, CA

- Ph.D. in Control and Dynamical Systems, 2002
- Thesis: *Control of Multiple Model Systems*

University of Arizona Tucson, AZ

- B.S. in Mathematics, *summa cum laude*, 1997

EMPLOYMENT

Northwestern University 2009-present
Professor 2017 - present
Associate Professor 2011-2017
Assistant Professor 2009-2011

University of Colorado at Boulder 2004-2008
Assistant Professor

Aerospace Corporation 2003-2004
Senior Technical Staff

Northwestern University 2002-2003
Postdoctoral Scholar

AWARDS AND HONORS

- Defense Science Study Group (DSSG)—one of fifteen scientists/engineers nationwide selected to participate in the DARPA/IDA DSSG for the two year program in 2014-2015
- Charles Deering McCormick Professor of Teaching Excellence—one of three awarded across the university—in 2014
- Invited speaker on Massive Open Online Courses (MOOCs) in universities for National Academy of Engineering Frontiers of Engineering Education Symposium in 2013
- National Science Foundation CAREER award in 2006

PUBLICATIONS¹ AND SOFTWARE

Journal Articles

- [38] A. Mavrommati, E. Tzorakoleftherakis, I. Abraham, and T. D. Murphey, “Real-time area coverage and target localization using receding-horizon ergodic exploration,” *IEEE Transactions on Robotics*, vol. 34, no. 1, 2018, To Appear.
- [37] M. A. MacIver, L. Schmitz, U. Mugan, T. D. Murphey, and C. D. Mobley, “A massive increase in visual range preceded the origin of terrestrial vertebrates,” *Proceedings of the National Academy of Science (PNAS)*, vol. 114, no. 12, pp. E2375–E2384, 2017.
- [36] I. Abraham, A. Prabhakar, M. Hartmann, and T. Murphey, “Ergodic exploration using binary sensing for non-parametric shape estimation,” *IEEE Robotics and Automation Letters*, vol. 2, no. 2, pp. 827–834, 2017.
- [35] A. D. Wilson, J. A. Schultz, A. Ansari, and T. D. Murphey, “Dynamic task execution using active parameter identification with the Baxter research robot,” *IEEE Transactions on Automation Science and Engineering*, vol. 14, no. 1, pp. 391–397, 2017.
- [34] K. Flaßkamp, A. Ansari, and T. D. Murphey, “Hybrid control for tracking of invariant manifolds,” *Nonlinear Analysis: Hybrid Systems*, vol. 25, pp. 298–311, 2017.
- [33] J. Schultz, K. Flaßkamp, and T. D. Murphey, “Variational integrators for structure-preserving filtering,” *ASME Journal of Computational and Nonlinear Dynamics*, vol. 12, no. 2, pp. 021005:1–021005:10, 2016.
- [32] A. Broad, M. Derry, J. Schultz, T. Murphey, and B. Argall, “Trust adaptation leads to lower control effort in shared control of crane automation,” *IEEE Robotics and Automation Letters*, vol. 2, no. 1, pp. 239–246, 2016.
- [31] A. Ansari and T. D. Murphey, “Sequential Action Control: Closed-form optimal control for nonlinear and nonsmooth systems,” *IEEE Transactions on Robotics*, vol. 32, no. 5, pp. 1196–1214, 2016.
- [30] A. Farshchiansadegh, A. Melendez-Calderon, R. Ranganathan, T. D. Murphey, and F. Mussa-Ivaldi, “Sensory agreement guides energy optimization in human movements,” *PLOS Computational Biology*, vol. 12, no. 4, p. e1004861, 2016.
- [29] A. Mavrommati, J. Schultz, and T. D. Murphey, “Real-time mode scheduling using single-integration hybrid optimization for linear time-varying systems,” *IEEE Transactions on Automation Science and Engineering*, vol. 13, no. 3, pp. 1385–1398, 2016.
- [28] E. Tzorakoleftherakis, T. D. Murphey, and R. A. Scheidt, “Augmenting sensorimotor control using goal-aware vibrotactile stimulation during reaching and manipulation behaviors,” *Experimental Brain Research*, vol. 234, no. 8, pp. 2403–2414, 2016.
- [27] A. Ansari and T. D. Murphey, “Minimum sensitivity control for planning with parametric and hybrid uncertainty,” *International Journal of Robotics Research*, vol. 35, no. 7, pp. 823–839, 2016.
- [26] E. Tzorakoleftherakis, A. Ansari, A. Wilson, J. Schultz, and T. D. Murphey, “Model-based reactive control for hybrid and high-dimensional robotic systems,” *IEEE Robotics and Automation Letters*, vol. 1, no. 1, pp. 431–438, 2016.
- [25] T. Caldwell and T. D. Murphey, “Projection-based iterative mode scheduling for switched systems,” *Nonlinear Analysis: Hybrid Systems*, vol. 21, pp. 59–83, 2016.
- [24] L. Miller, Y. Silverman, M. A. MacIver, and T. Murphey, “Ergodic exploration of distributed information,” *IEEE Transactions on Robotics*, vol. 32, no. 1, pp. 36–52, 2016.

¹Reprints of many of these can be found at <http://nrx.northwestern.edu/people/todd-murphey>

- [23] D. Pekarek and T. D. Murphey, “Discrete Lagrangian mechanics for nonsmooth nonseparable systems,” *International Journal for Numerical Methods in Engineering*, vol. 105, pp. 440–463, 2016.
- [22] R. Abbott, A. Pedler, M. Sterling, J. Hides, T. D. Murphey, M. Hoggarth, and J. Elliott, “The geography of fatty infiltrates within the cervical multifidus and semispinalis cervicis in individuals with chronic whiplash-associated disorders,” *Journal of Orthopaedic and Sports Physical Therapy*, vol. 45, no. 4, pp. 281–288, 2015.
- [21] E. Johnson, J. Schultz, and T. D. Murphey, “Linearizations of variational integrators for analysis and optimization,” *IEEE Transactions on Automation Science and Engineering*, vol. 12, no. 1, pp. 140–152, 2015.
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- [19] A. Wilson, J. Schultz, and T. D. Murphey, “Trajectory synthesis for Fisher information maximization,” *IEEE Transactions on Robotics*, vol. 30, no. 6, pp. 1358–1370, 2014.
- [18] B. Quist, V. Seghete, L. Huet, T. D. Murphey, and M. J. Z. Hartmann, “Modeling forces and moments at the base of a rat vibrissa during non contact whisking and whisking against an object,” *Journal of Neuroscience*, vol. 34, pp. 9828–9844, July 2014.
- [17] V. Seghete and T. D. Murphey, “Uniqueness conditions for simultaneous impact in locomotion: existence, uniqueness, and design consequences,” *IEEE Transactions on Automation Science and Engineering*, vol. 11, no. 1, pp. 154–168, 2014.
- [16] L. Miller and T. D. Murphey, “Simultaneous optimal estimation of mode transition times and parameters applied to simple traction models,” *IEEE Transactions on Robotics*, vol. 29, no. 6, pp. 1496–1503, 2013.
- [15] Y. P. Leong and T. D. Murphey, “Feature localization using kinematics and impulsive hybrid optimization,” *IEEE Transactions on Automation Science and Engineering*, vol. 10, no. 4, pp. 957 – 968, 2013.
- [14] T. Caldwell and T. D. Murphey, “Single integration optimization of linear time-varying switched systems,” *IEEE Transactions on Automatic Control*, vol. 57, no. 6, pp. 1592–1597, 2012.
- [13] E. Johnson and T. D. Murphey, “Second-order switching time optimization for nonlinear time-varying dynamic systems,” *IEEE Transactions on Automatic Control*, vol. 56, no. 8, pp. 1953–1957, 2011.
- [12] P. Martin, E. Johnson, T. D. Murphey, and M. Egerstedt, “Constructing and implementing motion programs for robotic marionettes,” *IEEE Transactions on Automatic Control*, vol. 56, no. 4, pp. 902–907, 2011.
- [11] T. Caldwell and T. D. Murphey, “Switching mode generation and optimal estimation with application to skid-steering,” *Automatica*, vol. 47, no. 1, pp. 50–64, 2011.
- [10] T. D. Murphey and J. Falcon, “Programming from the ground up in controls laboratories,” *International Journal of Engineering Education*, vol. 26, no. 5, pp. 1241–1248, 2010.
- [9] E. Jochum and T. D. Murphey, “A Robotic Pygmalion: Choreography for an automated marionette play,” *Puppetry International*, vol. 27, pp. 22–24, 2010.
- [8] E. Johnson and T. D. Murphey, “Scalable variational integrators for constrained mechanical systems in generalized coordinates,” *IEEE Transactions on Robotics*, vol. 25, no. 6, pp. 1249–1261, 2009.
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- [5] T. D. Murphey, “Teaching rigid body mechanics using student-created virtual environments,” *IEEE Transactions on Education*, vol. 51, no. 1, pp. 45–52, 2008.
- [4] T. D. Murphey, “On multiple model control for multiple contact systems,” *Automatica*, vol. 44, pp. 451–458, 2008.
- [3] T. D. Murphey, “Kinematic reductions for uncertain mechanical contact,” *Robotica*, vol. 25, pp. 751–764, Nov 2007.
- [2] T. D. Murphey and J. W. Burdick, “The power dissipation method and kinematic reducibility of multiple model robotic systems,” *IEEE Transactions on Robotics*, vol. 22, pp. 694–710, August 2006.
- [1] T. D. Murphey and J. W. Burdick, “Feedback control methods for distributed manipulation systems that involve mechanical contacts,” *International Journal of Robotics Research*, vol. 23, pp. 763–782, July 2004.

Peer Reviewed Conference Papers

- [110] T. Fan, H. Weng, and T. D. Murphey, “Decentralized and recursive identification for cooperative manipulation of unknown rigid body with local measurements,” in *IEEE Int. Conf. on Decision and Control (CDC)*, 2017.
- [109] I. Abraham, G. de la Torre, and T. Murphey, “Model-based control using Koopman operators,” in *Robotics: Science and Systems Proceedings*, 2017.
- [108] G. Mamakoukas, M. MacIver, and T. Murphey, “Feedback synthesis for controllable underactuated systems using sequential second order actions,” in *Robotics: Science and Systems Proceedings*, 2017.
- [107] A. Broad, T. Murphey, and B. Argall, “Learning models for shared control of human-machine systems with unknown dynamics,” in *Robotics: Science and Systems Proceedings*, 2017.
- [106] M. Castano, A. Mavrommati, T. D. Murphey, and X. Tan, “Trajectory planning and tracking of robotic fish using ergodic exploration,” in *American Controls Conf. (ACC)*, pp. 5476 – 5481, 2017.
- [105] A. Prabhakar, A. Mavrommati, J. Schultz, and T. D. Murphey, “Autonomous visual rendering using physical motion,” in *Workshop on the Algorithmic Foundations of Robotics (WAFR)*, 2016.
- [104] J. Schultz and T. D. Murphey, “Low-infrastructure real-time embedded control via variational integrators,” *PAMM*, vol. 16, no. 1, pp. 949–952, 2016.
- [103] G. De La Torre and T. D. Murphey, “On the benefits of surrogate Lagrangians in optimal control and planning algorithms,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 7384–7391, 2016.
- [102] A. Mavrommati and T. D. Murphey, “Automatic synthesis of control alphabet policies,” in *IEEE Int. Conf. on Automation Science and Engineering (CASE)*, pp. 313 – 320, 2016.
- [101] T. Fan and T. D. Murphey, “Online feedback control for input-saturated robotic systems on Lie groups,” in *Robotics: Science and Systems Proceedings*, 2016.
- [100] G. Mamakoukas, M. MacIver, and T. D. Murphey, “Controlling simulated underactuated underwater vehicles with added mass and velocity drift using sequential action control,” in *American Controls Conf. (ACC)*, pp. 4500 – 4506, 2016.

- [99] G. De La Torre, K. Flaßkamp, A. Prabhakar, and T. D. Murphey, “Ergodic exploration with stochastic sensor dynamics,” in *American Controls Conf. (ACC)*, pp. 2971 – 2976, 2016.
- [98] K. Fitzsimons, E. Tzorakoleftherakis, and T. D. Murphey, “Optimal human-in-the-loop interfaces based on Maxwell’s demon,” in *American Controls Conf. (ACC)*, pp. 4397 – 4402, 2016.
- [97] T. Fan and T. D. Murphey, “Structured linearization of discrete mechanical systems on Lie groups: a synthesis of analysis and control,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 1092 – 1099, 2015.
- [96] A. Prabhakar, K. Flaßkamp, and T. D. Murphey, “Symplectic integration for optimal ergodic control,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 2594 – 2600, 2015.
- [95] E. Tzorakoleftherakis and T. D. Murphey, “Controllers as filters: Noise-driven swing-up control based on Maxwell’s demon,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 4368 – 4374, 2015.
- [94] A. Wilson, J. Schultz, A. Ansari, and T. D. Murphey, “Real-time trajectory synthesis for information maximization using Sequential Action Control and least-squares estimation,” in *IEEE Int. Conf. on Intelligent Robots and Systems (IROS)*, pp. 4935–4940, 2015.
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- [92] A. Ansari, K. Flaßkamp, and T. D. Murphey, “Sequential action control for tracking of free invariant manifolds,” in *Analysis and Design of Hybrid Systems (ADHS)*, pp. 335–342, 2015.
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- [85] K. Flaßkamp and T. D. Murphey, “Variational integrators in linear optimal control and filtering,” in *American Controls Conf. (ACC)*, pp. 5140 – 5145, 2015.
- [84] T. Murphey and B. Argall, “Towards software-enabled rehabilitation,” in *IROS Workshop on Workshop on Rehabilitation & Assistive Robotics*, 2014.
- [83] I. D. Neveln, L. M. Miller, M. A. MacIver, and T. Murphey, “Improving object tracking through distributed exploration of an information map,” in *IEEE Int. Conf. on Intelligent Robots and Systems (IROS)*, pp. 3441 – 3447, 2014.

- [82] A. Mavrommati and T. D. Murphey, “Single-integration mode scheduling for linear time-varying switched systems,” in *American Controls Conf. (ACC)*, pp. 430 – 436, 2014.
- [81] E. Tzorakoleftherakis, F. Mussa-Ivaldi, R. Scheidt, and T. D. Murphey, “Effects of optimal tactile feedback in balancing tasks: a pilot study,” in *American Controls Conf. (ACC)*, pp. 778 – 783, 2014.
- [80] V. Seghete and T. D. Murphey, “Continuous-time optimal control of impacting mechanical systems via a projected Hamilton’s principle,” in *American Controls Conf. (ACC)*, pp. 2438 – 2444, 2014.
- [79] J. Schultz and T. D. Murphey, “Extending filter performance through structured integration,” in *American Controls Conf. (ACC)*, pp. 261 – 270, 2014.
- [78] A. Wilson and T. D. Murphey, “Local E-optimality conditions for trajectory design to estimate parameters in nonlinear systems,” in *American Controls Conf. (ACC)*, pp. 443 – 450, 2014.
- [77] E. Jochum, J. Schultz, and T. Murphey, “Engineering autonomous theatre: The impact of culture on mobile robots and automated systems,” in *AAMAS Workshop on Culture Aware Robotics*, 2014.
- [76] E. Jochum, G. Borggreen, and T. Murphey, “INTERACT: Applying theory and methods from the visual and performing arts to robots,” in *HRI-Workshop on Culture Aware Robotics*, 2014.
- [75] K. Flaßkamp, T. D. Murphey, and S. Ober-Blöbaum, “Optimization for discretized switched systems,” *PAMM*, vol. 13, no. 1, pp. 401–402, 2013.
- [74] T. Caldwell and T. D. Murphey, “Projection-based optimal mode scheduling,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 5307 – 5314, 2013.
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- [69] A. D. Wilson and T. D. Murphey, “Optimal trajectory design for well-conditioned parameter estimation,” in *IEEE Int. Conf. on Automation Science and Engineering (CASE)*, pp. 13–19, 2013. Finalist for ABB Best Conference Paper Award.
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- [65] J. Schultz and T. D. Murphey, “Embedded control synthesis using one-step methods in discrete mechanics,” in *American Controls Conf. (ACC)*, pp. 5293–5298, 2013.

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- [63] D. Pekarek and T. D. Murphey, “Global projections for variational nonsmooth mechanics,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 5572–5579, 2012.
- [62] L. Miller and T. D. Murphey, “Optimal contact decisions for ergodic exploration,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 5091–5097, 2012.
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- [60] K. Flaßkamp, T. D. Murphey, and S. Ober-Blobaum, “Switching time optimization in discretized hybrid dynamical systems,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 707–712, 2012.
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- [56] T. Caldwell and T. D. Murphey, “Projection-based switching time optimization,” in *American Controls Conf. (ACC)*, pp. 4552–4557, 2012.
- [55] T. D. Murphey and B. Argall, “Making robotic marionettes perform,” in *ICRA Workshop on Robotics and Performance Arts: Reciprocal Influences*, 2012.
- [54] B. Tovar and T. D. Murphey, “Trajectory tracking among landmarks and binary sensor beams,” in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, pp. 2121–2127, 2012.
- [53] V. Seghete and T. D. Murphey, “Conditions for uniqueness in simultaneous impact with application to mechanical design,” in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, pp. 5006–5011, 2012.
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- [21] T. D. Murphey, “Teaching rigid body mechanics using student-created virtual environments,” in *American Controls Conf. (ACC)*, pp. 2503–2508, 2007.
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- [15] B. Shucker, T. D. Murphey, and J. Bennett, “Cooperative control using occasional non-local interactions,” in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, pp. 1324–1329, 2006.
- [14] T. D. Murphey, J. Bernheisel, D. Choi, and K. M. Lynch, “An example of parts handling and self-assembly using stable limit sets,” in *IEEE Int. Conf. on Intelligent Robots and Systems (IROS)*, pp. 1624–1629, 2005.
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- [11] T. D. Murphey, D. Choi, J. Bernheisel, and K. M. Lynch, “Experiments in the use of stable limits sets for parts handling,” in *Proc. Int. Conf. MEMS, NANO, and Smart Systems (ICMENS)*, pp. 218–224, 2004.
- [10] T. D. Murphey and J. W. Burdick, “Kinematic reducibility for multiple model systems,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 5307–5313, 2003.
- [9] T. D. Murphey and J. W. Burdick, “Experiments in nonsmooth control of distributed manipulation,” in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, pp. 3600–3606, 2003.
- [8] T. D. Murphey and J. W. Burdick, “Smooth feedback control algorithms for fully actuated distributed manipulators,” in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, pp. 3619–3623, 2003.
- [7] T. D. Murphey and J. W. Burdick, “Nonsmooth controllability theory and an example,” in *IEEE Int. Conf. on Decision and Control (CDC)*, pp. 370–376, 2002.

- [6] T. D. Murphey and J. W. Burdick, "Global exponential stabilizability for distributed manipulation," in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, pp. 1210–1216, 2002.
- [5] T. D. Murphey and J. W. Burdick, "A local controllability test for nonlinear multiple model systems," in *American Controls Conf. (ACC)*, pp. 4657–4661, 2002.
- [4] T. D. Murphey and J. W. Burdick, "Global stability for distributed systems with changing contact states," in *IEEE Int. Conf. on Intelligent Robots and Systems (IROS)*, pp. 214–219, 2001.
- [3] T. D. Murphey and J. W. Burdick, "A controllability test and motion planning primitives for overconstrained vehicles," in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, pp. 2716–2722, 2001.
- [2] T. D. Murphey and J. W. Burdick, "On the stability and design of distributed systems," in *IEEE Int. Conf. on Robotics and Automation (ICRA)*, pp. 2686–2691, 2001.
- [1] T. D. Murphey and J. W. Burdick, "Issues in controllability and motion planning for overconstrained wheeled vehicles," in *Proc. Int. Conf. Math. Theory of Networks and Systems (MTNS)*, p. 8 pages, 2000.

Editor Reviewed Book Chapters

- [6] A. Mavrommati, A. Ansari, and T. D. Murphey, *Trends in Control and Decision-Making for Human-Robot Collaboration Systems*, ch. Assistive Optimal Control-on-Request with Application in Standing Balance Therapy and Reinforcement, pp. 131–156. Springer, 2017. Eds. Y. Wang and F. Zhang.
- [5] J. Schultz, E. Johnson, and T. D. Murphey, *Differential-Geometric Methods in Computational Multibody System Dynamics*, ch. Trajectory Optimization in Discrete Mechanics. CISM, 2015. Eds. Z. Terze and A. Mueller.
- [4] E. Jochum, J. Schultz, E. Johnson, and T. D. Murphey, *Art and Control*, ch. Robotic Puppets and the Engineering of Autonomous Theater. Springer-Verlag, 2013. Eds. A. LaViers and M. Egerstedt.
- [3] E. Jochum and T. D. Murphey, *New Scholarship on Puppetry and Performing Objects*, ch. Programming Play: Puppets, Robots, and Engineering. Springer-Verlag, 2012. Eds. D. Posner, J. Bell, and C. Orenstein.
- [2] T. D. Murphey, *Multi-point Interaction with Real and Virtual Objects*, ch. On Observing Contact States in Overconstrained Manipulation, pp. 151–164. Springer-Verlag, 2005. Eds. F. Barbagli, D. Prattichizzo, and K. Salisbury.
- [1] K. M. Lynch and T. D. Murphey, *Control Problems in Robotics and Automation*, ch. Control of Nonprehensile Manipulation, pp. 39–57. Springer-Verlag, 2003. Eds. A. Bicchi and H. Christensen.

Unrefereed Papers, Abstracts, and Posters

- [12] T. D. Murphey, "Sequential action control for nonlinear and hybrid systems," in *Proceedings of the Annual Meeting of the International Association of Applied Mathematics and Mechanics (GAMM)*, 2015.
- [11] J. Schultz and T. Murphey, "Real-time trajectory generation for a planar crane using discrete mechanics," in *IROS Workshop on Real-Time Systems*, 2014.
- [10] R. Abbott, A. Pedler, M. Sterling, J. Hides, T. Murphey, M. Hoggarth, and J. Elliott, "The distribution of muscle fat infiltration within the deep extensor muscles in whiplash-associated disorders," in *American Physical Therapy Association Combined Sessions Meeting: Orthopaedics*, 2015.

- [9] B. Argall and T. Murphey, “Computable trust in human instruction,” in *AAAI Symposium on AI for Human-Robot Interaction*, 2014.
- [8] T. D. Murphey, D. Pekarek, and V. Seghete, “Variational methods for contact mechanics,” in *Robotics Science and Systems Workshop: Toward High-Performance Computing Support for Simulation and Planning of Robot Contact Tasks*, 2011.
- [7] B. Quist, V. Seghete, T. D. Murphey, and M. Hartmann, “Modeling forces and moments at the vibrissal base during natural motion and collisions,” in *The Royal Society*, 2011.
- [6] G. S. Chirikjian, H. M. Choset, M. A. Morales, and T. D. Murphey, “Editorial: Special issue on eighth international workshop on the algorithmic foundations of robotics,” *International Journal of Robotics Research*, 2010.
- [5] T. D. Murphey, “Topology-based variational integration of degenerate interconnected mechanical systems,” in *European Conference on Computational Mechanics (ECCM)*, 2010.
- [4] T. D. Murphey, “Poster: Hybrid sensing with physical sensors,” in *Int. Conf. on Chaos and Nonlinear Dynamics*, 2010.
- [3] K. L. Snyder and T. D. Murphey, “Abstract: Mathematical tools for tracking uncertainty through gait,” in *Dynamic Walking: Principles and Concepts of Legged Locomotion*, 2009. 1 page.
- [2] E. Johnson and T. D. Murphey, “The automated marionette project,” in *AAAI Robotics and Creativity Workshop*, 2008.
- [1] T. D. Murphey and M. E. Egerstedt, “Choreography for marionettes: Imitation, planning, and control,” in *IEEE Int. Conf. on Intelligent Robots and Systems Workshop on Art and Robotics*, 2007. 6 pages.

Books

- [1] G. S. Chirikjian, H. M. Choset, M. A. Morales, and T. D. Murphey, eds., *Algorithmic Foundation of Robotics VIII*, vol. 57 of *Springer Tracts in Advanced Robotics*. Springer-Verlag, 2009.

Publicly Available Software

- [2] A. Ansari and T. D. Murphey. The SAC library for nonlinear control can be used for approximate optimal control of general nonlinear and nonsmooth systems. It is available at <https://github.com/alexansari101/saclib>.
- [1] E. Johnson, J. Schultz, and T.D. Murphey. The `trep` environment is a computation package for simulation and control of constrained mechanical systems. The `trep` environment is available at <https://github.com/MurpheyLab/trep>.

MEDIA AND ARTS

- Work featured in National Science Foundation *Science Nation* online magazine (2017).
- Video “Autonomous Robot Drawing: From Distributions to Actions using Feedback” third prize recipient in IEEE Control Systems Society video competition (2017).
- Talk: “Robot Artists and Automating Art” at the *Science Cafe* in Evanston IL (2017)
- Panelist for the Northwestern Master of Project Management Program Symposium *Robotics in the Built Environment*.
- Panelist for Volkenburg Puppetry Symposium *The Uncanny Valley: Real Fakeness and Fake Realness*.
- Op-Ed: “Creating Content for Many to Access a Few” in *Pacific Standard Magazine*, March, 2014.

- Talk: “Context and Liveness” at panel *The Uncanny Valley Revisited: A Tribute to Masuhiro Mori* at IROS (2013)
- Exhibit: laboratory robots (including robotic marionettes, Kinect interfaces, and rehabilitation robotics) featured in National Robotics Week exhibit at the Chicago Museum of Science and Industry (2013)
- Talk: “Robotic Puppets and Resisting Control” at the *ICRA Workshop on Art and Robotics: Freud’s Unheimlich and the Uncanny Valley, Germany, May, 2013*
- Talk: “Robotic Puppets and the Engineering of Autonomous Theater” at the *Science Cafe, Evanston, IL, April, 2013*
- Talk “Walk this Way!” (Primarily Andy Ruina’s talk, with my participation) at the *Science Caberet, Ithaca, NY, Feb. 2013*
- Talk: “Physical Animation: Control Design for Animatronic Marionettes” at the *IDETC/CIE panel on Entertainment Engineering, August, 2012*
- Exhibit: laboratory robots (including robotic marionettes and humanoid robots) featured in National Robotics Week exhibit at the Chicago Museum of Science and Industry (2012)
- Talk: “Making Marionettes Move” at the *Museum of Science and Industry, National Robotics Week, April, 2012*
- Talk: “The Reality of Robotics: Challenges of Everyday Robots.” at the *Museum of Science and Industry, Rosenwald Society Luncheon, Chicago, August, 2011*

INVITED TALKS

- ROBOT ARTISTS AND AUTOMATING ART. *Science Cafe, Evanston IL, Feb. 2017* — *Robotics: Science and Systems Workshop, Carnegie Mellon University, April, 2017* — *Buffet Institute Fellows Talk, Northwestern University, May 2017*
- PRINCIPLES OF STATISTICAL MECHANICS IN ALGORITHMIC DESIGN FOR SHARED AUTONOMY. *AAAI Fall Symposium Workshop on Shared Autonomy in Research and Practice, Nov. 2016* — *ICRA Workshop on Recent Advances in Dynamics for Industrial Applications, May 2017*
- COMPUTATIONAL CONTROL ENGINES FOR ROBOTIC SYSTEMS. *University of Illinois, IL, Feb. 2016* — *Midwest Robotics Workshop, IL, March 2016* — *Mathworks, MA, May 2016*
- CONTROL FOR INFORMATION ACQUISITION. *University of North Carolina, Charlotte, NC, Jan. 2014* — *Air Force Research Laboratory, NM, Aug. 2014* — *Feinberg School of Medicine, Northwestern University, July, 2015* — *Georgia Institute of Technology, GA, Aug. 2015* — *Michigan State University, MI, April, 2016* — *Massachusetts Institute of Technology, MA, May 2016* — *DARPA STO, Nov. 2016*
- OPEN OPERATING SYSTEMS IN LOW-INFRASTRUCTURE TESTBEDS. *NSF Workshop on Accessible Remote Testbeds, NSF, Nov., 2015*
- HIGH PERFORMANCE CONTROL USING LOW PERFORMANCE INFRASTRUCTURE. *Los Alamos National Laboratory, NM, Jan., 2015* — *Georgia Institute of Technology, GA, Feb., 2015* — *Ohio State University, October, 2015* —
- SEQUENTIAL ACTION CONTROL: CLOSED-FORM FEEDBACK CONTROL FOR NONLINEAR SYSTEMS. *Georgia Institute of Technology, GA, Oct., 2014*
- MOOCs AND ONLINE COURSES IN ENGINEERING EDUCATION. *National Academy of Engineering Frontiers of Engineering Education Workshop, Irvine, CA, Oct., 2013* — *ASME Congress Workshop, San Diego, CA, Nov., 2013* — *University of Maryland, MD, Jan. 2014* — *Notre Dame, IN, Sept. 2014*

- TOPOLOGY SCHEDULING FOR POWER NETWORK STABILITY. *Argonne National Laboratory, IL, March, 2013 — Argonne National Laboratory, IL, April, 2013 — Northwestern Institute for Complex Systems, IL, May, 2013*
- CONTROL SYNTHESIS FOR DISCRETE MECHANICAL SYSTEMS *Complex Systems Seminar, Northwestern University, Jan., 2012 — Michigan Institute of Technology, Sept., 2012 — Cornell University, NY, Feb., 2013*
- HYBRID CONTROL FOR MECHANICAL SYSTEMS. *University of Paderborn, Germany, Aug., 2011 — University of New Mexico, Albuquerque, Dec., 2011*
- CHOREOGRAPHY AND CONTROL FOR ROBOTIC SYSTEMS. *Robotics Institute, Carnegie Mellon University, Pittsburgh, PA, Oct., 2010. Available at <https://www.youtube.com/watch?v=i3jWwwISNPY>.*
- TOPOLOGY-BASED VARIATIONAL INTEGRATION OF DEGENERATE INTERCONNECTED MECHANICAL SYSTEMS. *Northwestern University, Evanston, Illinois, March, 2008 — ICRA Workshop on Modeling Contact in Manipulation and Locomotion, Pasadena, California, May, 2008 — AAI Robotics Workshop: Creativity and Robotics, Chicago, Illinois, July, 2008 — University of Wyoming, Oct. 2008 — Structured Integrator Workshop, May, 2009 — RSS Workshop on Algorithmic Automation, June, 2009 — Rehabilitation Institute of Chicago, Aug., 2009 — University of California, Berkeley, Feb. 2010 — Keynote Lecture: European Congress on Computational Mechanics - Symposium on Advanced Numerical Methods in Multibody Systems and Control, Apr. 2010*
- MODE ESTIMATION USING RELAXATIONS OF PROJECTIONS. *Applied Mathematics, Northwestern University, Oct. 2009 — Illinois Institute of Technology, Nov. 2009 — University of Illinois, Urbana-Champaign, Nov. 2009 — University of Pennsylvania, Jan. 2010*
- AUTOMATIC SYNTHESIS OF MOTION IMITATION IN MARIONETTES. *Northwestern University, Evanston, Illinois, May 2007 — IROS Workshop on Art and Robots, San Diego, California, Nov., 2007*

FUNDING

- Todd D. Murphey (PI) and Xiabo Tan. National Science Foundation–Information and Intelligent Systems: *RI: Small: Collaborative Research: Information-driven Autonomous Exploration in Uncertain Underwater Environments*. \$500,000.
- Todd D. Murphey (PI). National Science Foundation–Civil and Mechanical Systems: *Stability and Optimality Properties of Sequential Action Control for Nonlinear and Hybrid Systems*. \$375,000.
- Todd D. Murphey (PI). National Science Foundation–National Robotics Initiative: *Task-Based Assistance for Software-Enabled Biomedical Devices*. \$430,000.
- Todd D. Murphey (PI), Eva Kanso, Yasamin Mostofi, Evangelos Theodorou. Army Research Office: *Study Proposal: Transforming Terrestrial Agility At All Scales*. \$60,000.
- Mitra Hartmann (PI), Todd Murphey, John Rudnicki, Sara Solla. National Institutes of Health: *Coding properties of Vibrissal-Responsive Trigeminal Ganglion Neurons*. \$1,800,000.
- Todd D. Murphey. Army Research Office: *Ergodic Control for Optimal Information Acquisition*. \$360,000.

- Todd D. Murphey (PI, 50%), J. Edward Colgate (Co-PI, 50%). National Science Foundation–National Robotics Initiative: *Autonomous Synthesis of Haptic Languages*. \$585,000.
- Malcolm A. MacIver (PI, 40%), Michael Peshkin (Co-PI, 30%), Todd D. Murphey (Co-PI, 30%). Office of Naval Research: *A Bio-Inspired Underwater Robot for Station Keeping with Omnidirectional Disturbances*. \$1,000,000.
- Todd D. Murphey (PI, 35%), Brenna Argall (Co-PI, 35%), and Magnus Egerstedt (Co-PI, 30%). National Science Foundation–Civil and Mechanical Systems: *Collaborative Research: Mutually stabilized correction in physical demonstration*. \$1,000,000.
- Todd D. Murphey (PI, 50%) and Melvin Leok (Co-PI, 50%). National Science Foundation–Civil and Mechanical Systems: *Ergodic Trajectories in Discrete Mechanics*. \$430,000.
- Todd D. Murphey. National Institute of Health–R24: *Exoskeleton Evaluation for Hemiplegia Therapy*. \$50,000.
- Todd D. Murphey. National Science Foundation–Civil and Mechanical Systems: *Physical Design and Feedback Control of Hybrid Mechanical Systems*. \$350,000.
- Kevin Lynch (PI), Brenna Argall, J. Edward Colgate, Todd D. Murphey, and Ying Wu (Co-PIs). National Science Foundation: *MRI: Equipment Development: Bimanual Robotic Manipulation and Sensory Workspace*. \$400,000.
- Todd D. Murphey (PI, 50%) and Kevin Lynch (Co-PI, 50%). National Science Foundation–Robust Intelligence: *Hierarchical Planning, Estimation, and Control for Hybrid Mechanical Systems*. \$450,000.
- W. Murray (PI, 50%), T. D. Murphey (Co-PI, 50%), National Institutes of Health: *Prosthesis Control by Forward Simulation of the Intact Biomedical System*. (Northwestern portion) \$550,000.
- Todd D. Murphey (Consultant to Kinea, 10%) DARPA: *SBIR Phase I: Tactile Detection Robotic Hand System*. Murphey’s portion is \$10,000
- Todd D. Murphey (PI, 50%) and Magnus Egerstedt (Co-PI, 50%). National Science Foundation–CreativeIT: *Collaborative Research: Major: Puppet Choreography and Automated Marionettes*. \$800,000.
- Magnus Egerstedt (Co-PI, 50%) and Todd D. Murphey (PI, 50%). National Science Foundation–Software for Real-World Systems: *Collaborative Proposal: Abstraction-Based Motion Programs for Complex, Interconnected Systems*. \$450,000.
- Lucy Y. Pao (PI, 50%) and Todd D. Murphey (Co-PI, 50%). Air Force Research Laboratory: *Data Association and Sensor Management Algorithms for Tracking Applications*. \$250,000.
- Todd D. Murphey. National Science Foundation–Advanced Learning Technology: *Assessment of Controls Laboratory*. \$24,591.
- Todd D. Murphey. National Science Foundation–Civil and Mechanical Systems: *CAREER: Planning and Control for Overconstrained Mechanisms*. \$400,000.

TEACHING

Teaching Highlights

- Northwestern University Cole-Higgins Award for Excellence in Teaching (2015)
- Northwestern University Charles Deering McCormick Professor of Teaching Excellence (2014)

- Northwestern University Cole-Higgins Award for Excellence in Advising (2013)
- Participant in National Academy of Engineering Frontiers of Engineering Education Symposium (2009)
- Searle Fellow at Northwestern University (2009-2010)
- Bruce Holland Excellence in Teaching award (2007) (ECE Department at CU Boulder)

Coursera

2013-2014, www.coursera.org

- Created and taught course: *Everything Is The Same: Modeling Engineered Systems*; available at <http://www.coursera.org/course/modelsystems>.

International Centre for Mechanical Sciences (CISM)

2013, Udine, Italy

- Lecturer for *Differential-Geometric Methods in Computational Multibody Systems*. (My portion of the lectures focused on engineering applications of structured integration and optimal control in the context of structured integration.)

Northwestern University

2009-present, Evanston, IL

- Created and taught course: *Theory of Machines: Dynamics ME 314* (2009-2016)
- Taught course: *Systems Dynamics, EA-3* (2009-2016)
- Created and taught course: *Introduction to Optimal Control, ME 454* (2009-2016)
- Created and taught course: *Stochastic Systems in Robotics* (Spring, 2011)

University of Colorado

2004-2008, Boulder, CO

- Created and taught course: *Engineering Freshman Honors Colloquium: Everything and More—A History of Limits and the Development of Modern Calculus* (Spring 2008)
- Created and taught course: *Engineering Freshman Projects: Algorithms in Robotics, GEEN 1400* (Fall 2007, 2008)
- Created and taught course: *Introduction to Geometric Mechanics and Control ECEN 4028/5028* (Spring 2006)
- Created and taught course: *Robot Dynamics and Motion Planning ECEN 4028/5028* (Spring 2006)
- Taught course: *Control Systems Analysis ECEN 4138* (Fall 2005, 2006)
- Created and taught laboratory: *Control Systems Lab ECEN 4638* (Fall 2005, 2006, 2007, 2008)
- Created and taught course: *Robot Control ECEN 5438* (Spring 2005, 2007)

PROFESSIONAL ACTIVITIES**Service Highlights**

- Member: National Academies / National Research Council Committee on Counter-Unmanned Aircraft System (CUAS) Capability for Battalion-and-Below Operations (2016)
- Member: National Institute of Aerospace study on *Analysis of Vehicle Automation Supporting Remotely Managed, Small, Passenger-Carrying Autonomous Aircraft* (2016)
- Presented at the Coalition for the National Science Foundation (CNSF) Capitol Hill Exhibition (2017)
- Senior Editor for *IEEE Transactions on Robotics* (2014-present)

- Member: Northwestern University Task Force on the Undergraduate Academic Experience (2015)

University Service

- Chair: Northwestern University Faculty Distance Learning Workgroup (2015 - present)
- Member: Distance Learning Planning Committee (2017 - present)
- Director and Co-Founder of Master of Science in Robotics Program (2013-present)
- Member: Northwestern University Segal Design Institute Research Council
- Member: Feinberg School of Medicine DPT/PhD T32 Steering Committee
- Participant in Kellogg School of Management Executive Education 2013 Program *Management Skills for Innovative University Leaders*.

External Service

- Associate Editor for
 - *IEEE Transactions on Automation Science and Engineering* (2010-present)
 - *IEEE Transactions on Robotics* (2008-2012)
 - *Robotica* (2007-2011)
- Member: University of Copenhagen *Robot Culture and Aesthetics* Advisory Board
- Conference Organization
 - Local Arrangements Chair for the 2014 *IEEE International Conference on Intelligent Robots and Systems (IROS)*
 - Publication Chair for the 2010 *IEEE International Conference on Automation Science and Engineering (CASE)*
 - Co-Organizer (with Greg Chirikjian, Howie Choset, and Marco Morales) of 2008 *Workshop on the Algorithmic Foundations of Robotics (WAFR)*
- Workshop Organization
 - Co-Organizer (with Ken Goldberg, Vijay Kumar, and Frank van der Stappen) of 2009 *RSS Workshop on Algorithmic Automation*
 - Co-Chair (with Ken Goldberg, Jean-Paul Laumond, and Vijay Kumar) of CASE 2008 workshop: *Workshop on Algorithmic Automation*
 - Co-Organizer (with Vijay Kumar) of ICRA 2008 workshop: *Contact Models for Manipulation and Locomotion*
 - Co-Organizer (with Francisco Valero-Cuevas and Yoky Matsuoka) of ICRA 2008 workshop: *Is human-like dextrous manipulation within our robotic grasp?*
- Participant in the National Science Foundation and Computing Community Consortium (CCC) *Workshop on Robotics in Manufacturing and Automation*
- Conference Program committees
 - 2017 *Robotics: Science and Systems*: Area Chair
 - 2016 *Robotics: Science and Systems*: Area Chair
 - 2016 *Workshop on the Algorithmic Foundations of Robotics*
 - 2015 *IFAC Conference on Analysis and Design of Hybrid Systems*
 - 2012 *Workshop on the Algorithmic Foundations of Robotics*
 - 2009 *Robotics: Science and Systems*
 - 2008 *Hybrid Systems: Computation and Control*
 - 2008 *Robotics: Science and Systems*
 - 2008 *IEEE International Conference on Robotics and Automation*
 - 2008 *IEEE Conference on Automation Science and Engineering*
 - 2007 *IEEE/RSJ International Conference on Intelligent Robots and Systems*

- 2007 *International Conference on Advanced Robotics*
- 2007 *International Conference on Networked Robots*
- 2007 *IEEE International Conference on Robotics and Automation*
- 2006 *IEEE/RSJ International Conference on Intelligent Robots and Systems*
- 2006 *IEEE International Conference on Robotics and Automation*
- 2005 *Robotics: Science and Systems*
- 2005 *IEEE/RSJ International Conference on Intelligent Robots and Systems*
- 2001 *IEEE/RSJ International Conference on Intelligent Robots and Systems*
- Other Conference Committees
 - ICRA Best Student Paper 2012 (Chair)
 - CASE Best Paper 2010
 - ICRA Best Student Paper 2008
- National Science Foundation Panelist for programs ranging from control, education, robotics, cyberphysical systems, and others 2006-2016
- Member, IEEE, and ASME

STUDENTS AND POSTDOCS ADVISED

- Postdocs
 - Dr. Gerardo de la Torre (ME at Northwestern University), now at Northrop Grumman
 - Dr. Kathrin Flaßkamp (ME at Northwestern University), now a Postdoctoral Researcher at the University of Bremen
 - Dr. David Pekarek (ME at Northwestern University), now a senior scientist at Data Tactics
 - Dr. Benjamin Tovar (ME at Northwestern University), now a Research Software Engineer at Notre Dame
- Ph.D. Students
 - Brian Shucker (CS at University of Colorado), 2006 Ph.D. thesis: *Control of Distributed Robotic Macrosensors*, was at MIT Lincoln Laboratories, now at TALOS robotics.
 - Matt Travers (ME at Northwestern University), 2011 Ph.D. thesis: *Impulse Smoothing for Data Association*, now a Systems Scientist at Carnegie Mellon University.
 - Elliot Johnson (ME at Northwestern University), 2012 Ph.D. thesis: *Trajectory Optimization and Regulation for Constrained Discrete Mechanical Systems*, now at the Southwester Research Institute.
 - Elizabeth Jochum (Performance Studies at the University of Colorado), 2013 Ph.D. thesis: *Deux Ex Machina: Towards an Aesthetics of Autonomous and Semi-Autonomous Machines*, now an Assistant Professor at Aalborg University.
 - Tim Caldwell (ME at Northwestern University), 2013 Ph.D. thesis: *Iterative Methods in Switched System Optimal Control*, previously a postdoc at the University of Colorado at Boulder and now at Zoox (a driverless car startup company).

- Vlad Seghete (ME at Northwestern University), 2014 Ph.D. thesis: *Numerical Methods for Simulation and Control of Impacting Mechanical Systems*. Now at DataScope Analytics.
- Jarvis Schultz (ME at Northwestern University), 2014 Ph.D. thesis: *Discrete Mechanics Computation for Real-Time Embedded Control*, now at Northwestern University.
- Andrew Wilson (ME at Northwestern University) 2015 Ph.D. thesis: *Information-based Trajectory Optimization for Active Estimation in Mechanical Systems*, now at Intuitive Surgical.
- Alex Ansari (ME at Northwestern University), 2015 Ph.D. thesis: *Sequential Action Control: Closed-Form Optimal Feedback for Nonlinear and Hybrid Systems*. Now a postdoc at Carnegie Mellon University.
- Lauren Miller (ME at Northwestern University), 2015 Ph.D. thesis: *Optimal Ergodic Control for Active Search and Information Acquisition*. Postdoc at UC Berkeley 2015-2016. Now at HERE (a driverless car software company).
- Anastasia Mavrommati (ME at Northwestern University), 2017 Ph.D. thesis: *Real-Time Algorithms for Symbol-Based Automation*. Now at Schlumberger-Doll Research.
- Emmanouil Tzorakoleftherakis (ME at Northwestern University), 2017 Ph.D. thesis: *Stable Control Synthesis for Human-in-the-Loop Systems*. Now at Mathworks.
- Rebecca Abbott (ME/Physical Therapy at Northwestern University, co-advised with Prof. James Elliot.)
- Ahalya Prabhakar (ME at Northwestern University)
- Kathleen Fitzsimons (ME at Northwestern University)
- Giorgos Mamakoukas (ME at Northwestern University)
- Taosha Fan (ME at Northwestern University)
- Ian Abraham (ME at Northwestern University)
- Aleksandra (Ola) Kalinowska (ME at Northwestern University)
- Ana Pervan (ME at Northwestern University)
- Alfonso Fernandez (ME at Northwestern University)
- Undergraduate and MS Students
 - Kirk Nichols (ECE at University of Colorado), now a graduate student at Stanford
 - Corrina Gibson (Aerospace at University of Colorado), now at the Jet Propulsion Laboratory
 - Matanya Horowitz (ECE at University of Colorado), now a graduate student at Caltech
 - Yoke Peng Leong (ME at Northwestern University), now a graduate student at Caltech
 - Katy Powers (ME at Northwestern University), now a graduate student at the University of Pennsylvania

- Henry Hung (ME at Northwestern University)
- Camaria Lehman (BME at Northwestern University)
- Elliot Hevel (ME at Northwestern University)
- Scott Beck (ME at Northwestern University)
- Vismaya Walawalker (ME at Northwestern University)
- Samuel Donis (ME at Northwestern University)
- Visiting Students
 - Amy LaViers (Georgia Institute of Technology, USA)
 - Rowland O'Flaherty (Georgia Institute of Technology, USA)
 - Kathrin Flasskamp (Univ. of Paderborn, Germany)
 - Peter Kingston (Georgia Institute of Technology, USA)

EXTERNAL ACTIVITIES

- Consultant for HDT for SOCOM TALOS exoskeleton project (2016-2017)
- Member of Nousot Scientific Advisory Board (2017-)